

The background of the entire page is a deep space image. The top half features a dark blue and black sky filled with numerous small, distant stars. A prominent, bright star with a four-pointed diffraction pattern is visible in the upper left. The bottom half of the image shows a more complex scene with a large, glowing nebula in shades of orange, red, and yellow, set against a darker blue background with more stars. The text is overlaid on the upper half of this image.

CPSC 542F WINTER 2017

Convex Analysis and Optimization

Lecture Notes

SUMMER RESEARCH INTERNSHIP, UNIVERSITY OF WESTERN ONTARIO

[GITHUB.COM/LAURETHTEX/CLUSTERING](https://github.com/LAURETHTEX/CLUSTERING)

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1. Convex Sets

1.1 Convexity

1.1.1 Cone

■ **Definition 1.1.1 — Cone.** A set $K \in \mathbb{R}^n$, when $x \in K$ implies $\alpha x \in K$.

A non convex cone can be hyper-plane.

For convex cone $x + y \in K, \forall x, y \in K$.

Cone don't need to be "pointed". e.g.

Direct sums of cones $C_1 + C_2 = \{x = x_1 + x_2 | x_1 \in C_1, x_2 \in C_2\}$.

■ **Example 1.1** $S_1^n \{X | X = X^n, \lambda(x) \geq 0\}$

A matrix with positive eigenvalues. ■

Operations preserving convexity

Intersection $C \cap_{i \in I} C_i$

Linear map Let $A : \mathbb{R}^n \rightarrow \mathbb{R}^n$ be a linear map. If $C \in \mathbb{R}^n$ is convex, so is $A(C) = \{Ax | x \in C\}$

Inverse image $A^{-1}(D) = \{x \in \mathbb{R}^n | Ax \in D\}$

Operations that induce convexity

Convex hull on $S = \cap \{C | S \in C, C \text{ is convex}\}$

■ **Example 1.2** $Co\{x_1, x_2, \dots, x_m\} = \{\sum_{i=1}^m \alpha_i x_i | \alpha_i \in \delta_m\}$ ■

For a convex set $x \in C \Rightarrow x = \sum \alpha_i x_i$.

Theorem 1.1.1 — Carathéodory's theorem. If a point $x \in \mathbb{R}^d$ lies in the convex hull of a set P , there is a subset P' of P consisting of $d + 1$ or fewer points such that x lies in the convex hull of P' . Equivalently, x lies in an r -simplex with vertices in P .

1.2 Convex Functions

Definition 1.2.1 — Convex function. Let $C \subseteq \mathbb{R}^n$ be convex, $f : C \rightarrow \mathbb{R}$ is convex on f if $x, y \in C \times C$. $\forall \alpha \in (0, 1)$, $f(\alpha x + (1 - \alpha)y) \leq \alpha f(x) + (1 - \alpha)f(y)$

Definition 1.2.2 — Strictly Convex function. Let $C \subseteq \mathbb{R}^n$ be convex, $f : C \rightarrow \mathbb{R}$ is strictly convex on f if $x, y \in C \times C$. $\forall \alpha \in (0, 1)$, $f(\alpha x + (1 - \alpha)y) < \alpha f(x) + (1 - \alpha)f(y)$

Definition 1.2.3 — Strongly convex. $f : C \rightarrow \mathbb{R}$ is strongly convex with modulus $u \geq 0$ if $f - \frac{1}{2}u\|\cdot\|^2$ is convex.

Interpretation: There is a convex quadratic $\frac{1}{2}u\|\cdot\|^2$ that lower bounds f .

■ **Example 1.3** $\min_{x \in C} f(x) \leftrightarrow \min \bar{f}(x)$ Useful to turn this into an unconstrained problem.

$$\bar{f}(x) = \begin{cases} f(x) & \text{if } x \in C \\ \infty & \text{elsewhere} \end{cases}$$

■ **Definition 1.2.4** A function $f : \mathbb{R}^n \rightarrow \mathbb{R} \cup \infty$ is convex if $x, y \in \mathbb{R}^n$, $\forall x, y, \bar{f}(\alpha x + (1 - \alpha)y) \leq \alpha \bar{f}(x) + (1 - \alpha)\bar{f}(y)$

Definition 1 is equivalent to definition 2 if $f(x) = \infty$.

■ **Example 1.4** $f(x) = \sup_{j \in J} f_j(x)$ ■

1.2.1 Epigraph

Definition 1.2.5 — Epigraph. For $f : \mathbb{R}^n \rightarrow \bar{\mathbb{R}}$, its epigraph $\text{epi}(f) \in \mathbb{R}^{n+1}$ is the set $\text{epi}(f) = \{(x, \alpha) \mid f(x) \leq \alpha\}$

Next: a function is convex i.f.f. its epigraph is convex.

Definition 1.2.6 A function $f : C \rightarrow \mathbb{R}$, $C \subseteq \mathbb{R}^n$ is convex if $\forall x, y \in C$, $f(ax + (1 - a)x) \leq af(x) + (1 - a)f(y)$ $\forall a \in (0, 1)$.

Strict convex: $x \neq y \Rightarrow f(ax + (1 - a)x) < af(x) + (1 - a)f(y)$

R f is convex $\Rightarrow -f$ is concave.

Level set: $S_\alpha f = \{x \mid f(x) \leq \alpha\}$.

$S_\alpha f$ is convex $\Leftrightarrow f$ is convex.

Definition 1.2.7 — Strongly convex. $f : C \rightarrow \mathbb{R}$ is strongly convex with modulus μ if $\forall x, y \in C$, $\forall \alpha \in (0, 1)$, $f(ax + (1 - \alpha)x) \leq \alpha f(x) + (1 - \alpha)f(y) - \frac{1}{2\mu}\alpha(1 - \alpha)\|x - y\|^2$.

- R**
- f is 2nd-differentiable, f is convex $\Leftrightarrow \nabla^2 f(x) \succeq 0$.
 - f is strongly convex $\Leftrightarrow \nabla^2 f(x) \succeq \mu I \Leftrightarrow x \succeq \mu$

Definition 1.2.8 — 2. $f : \mathbb{R}^n \rightarrow \bar{\mathbb{R}}$ is convex if $x, y \in \mathbb{R}, \alpha \in (0, 1), f(ax + (1 - \alpha)x) \leq \alpha f(x) + (1 - \alpha)f(y)$.

The effective domain of f is $\text{dom} f = \{x | f(x) < +\infty\}$

■ **Example 1.5 — Indicator function.** $\delta_C(x) = \begin{cases} 0 & x \in C \\ +\infty & \text{elsewhere} \end{cases}$.
 $\text{dom} \delta_C(x) = C$ ■

Definition 1.2.9 — Epigraph. The epigraph of f is $\text{epi} f = \{(x, \alpha) | f(x) \leq \alpha\}$

The graph of $\text{epi} f$ is $\{(x, f(x)) | x \in \text{dom} f\}$.

Definition 1.2.10 — III. A function $f : \mathbb{R}^n \rightarrow \bar{\mathbb{R}}$ is convex if $\text{epi} f$ is convex.

Lemma 1.2.1 $f : \mathbb{R}^n \rightarrow \bar{\mathbb{R}}$ is convex $\iff \forall x, y \in \mathbb{R}^n, \alpha \in (0, 1), f(ax + (1 - \alpha)x) \leq \alpha f(x) + (1 - \alpha)f(y)$.

Proof. $\Rightarrow$ take $x, y \in \text{dom} f, (x, f(x)) \in \text{epi} f, (y, f(y)) \in \text{epi} f$.

Because $\text{epi} f$ is convex, $\alpha(x, f(x)) + (1 - \alpha)(y, f(y)) \in \text{epi} f$. $\alpha x + (1 - \alpha)y, \alpha f(x) + (1 - \alpha)f(y) \in \text{epi} f$ ■

■ **Example 1.6 — Distance.** Distance to a convex set $d_C(x) = \inf_{z \in C} \|z - x\|$. Take any two sequence $\{y_k\}$ and $\{\bar{y}_k\} \subset C$ s.t. $\|y_k - x\| \rightarrow d_C(x), \|\bar{y}_k - \bar{x}\| \rightarrow d_C(\bar{x})$. $z_k = \alpha y_k + (1 - \alpha)\bar{y}_k$.

$$\begin{aligned} d_C(\alpha x + (1 - \alpha)\bar{x}) &\leq \|z_k - \alpha x - (1 - \alpha)\bar{x}\| \\ &= \|\alpha(y_k - x) + (1 - \alpha)(\bar{y}_k - \bar{x})\| \\ &\leq \alpha\|y_k - x\| + (1 - \alpha)\|\bar{y}_k - \bar{x}\| \end{aligned}$$

Take $k \rightarrow \infty, d_C(\alpha x + (1 - \alpha)\bar{x}) \leq \alpha d_C(x) + (1 - \alpha)d_C(\bar{x})$ ■

■ **Example 1.7 — Eigenvalues.** Let $X \in S^n := \{n \times n \text{ symmetric matrix}\}$. $\lambda_1(x) \geq \lambda_2(X) \geq \dots \geq \lambda_n(x)$.

$$f_k(x) = \sum_{i=1}^n \lambda_i(x).$$

Equivalent characterization

$$\begin{aligned} f_k(x) &= \max \left\{ \sum_i v_i^T X v_i \mid v_i \perp v_j, i \neq j \right\} \\ &= \max \{ \text{tr}(V^T X V) \mid V^T V = I_k \} \\ &= \max \{ \text{tr}(V V^T X) \} \text{ by circularity} \end{aligned}$$

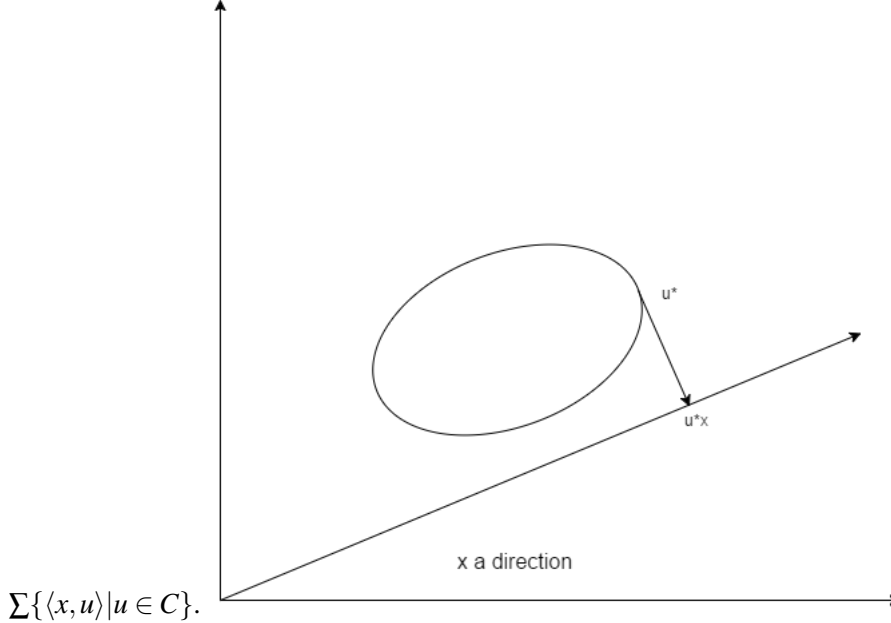
Note $\langle A, B \rangle = \text{tr}(A, B)$ is true for symmetric matrix.

$$\langle A, A \rangle = \|A\|_F^2 = \sum_i A_{ii}^2$$

■

1.3 Support Function

Take a set $C \in \mathbb{R}^n$, not necessarily convex. The support function is $\sigma_C = \mathbb{R}^n \rightarrow \bar{\mathbb{R}}$. $\sigma_C(x) =$



Fact 1.3.1 The support function binds the supporting hyper-plane.

Supporting functions are

- Positively homogeneous
 $\sigma_C(\alpha x) = \alpha \sigma_C(x) \forall \alpha \geq 0$
 $\sigma_C(\alpha x) = \sup_{u \in C} \langle \alpha x, u \rangle = \alpha \sup_{u \in C} \langle x, u \rangle = \alpha \sigma_C(x)$
- Sub-linear (a special case of convex, linear combination holds $\forall \alpha$).
 $\sigma_C(\alpha x + (1 - \alpha)y) = \sup_{u \in C} \langle \alpha x + (1 - \alpha)y, u \rangle \leq \alpha \sup_{u \in C} \langle x, u \rangle + (1 - \alpha) \sup_{u \in C} \langle y, u \rangle$

■ **Example 1.8 — L2-norm.** $\|x\| = \sup_{u \in C} \{ \langle x, u \rangle, u \in \mathbb{R}^n \}$.

$\|x\|_p = \sup \{ \langle x, u \rangle, u \in B_q \}$ where $\frac{1}{p} + \frac{1}{q} = 1$. $B_q = \{ \|x\|_q \leq 1 \}$.

The norm is

- Positive homogeneous
- sub-linear
- If $0 \in C$, σ_C is non-negative.
- If C is central-symmetric, $\sigma_C(0) = 0$ and $\sigma_C(x) = \sigma_C(-x)$

■

Fact 1.3.2 — Epigraph of a support function is a cone. Epigraph of a support function

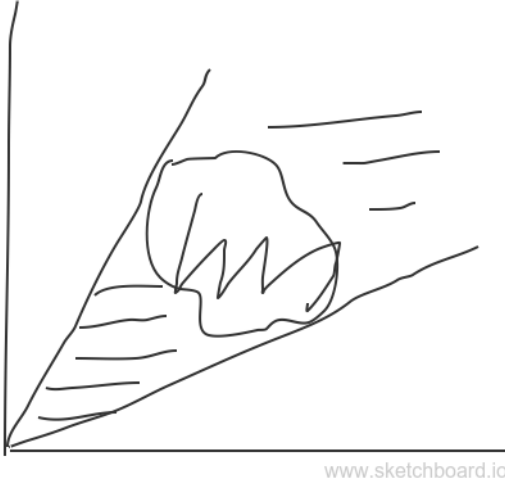
$epi\sigma_C = \{ (x, t) | \sigma_C(x) \leq t \}$. Take any $\alpha > 0$, $\alpha(x, t) = (\alpha x, \alpha t)$.

$\sigma_C(\alpha x) = \alpha \sigma_C(x) \leq \alpha t$.

$\Rightarrow \alpha(x, t) \in epi\sigma_C$

$$\begin{aligned}
 f \circ A(x) &= f(A(\alpha x + (1 - \alpha)y)) \\
 &= f(A\alpha x + (1 - \alpha)Ay) \\
 &\leq \alpha f(Ax) + (1 - \alpha)f(Ay)
 \end{aligned}$$

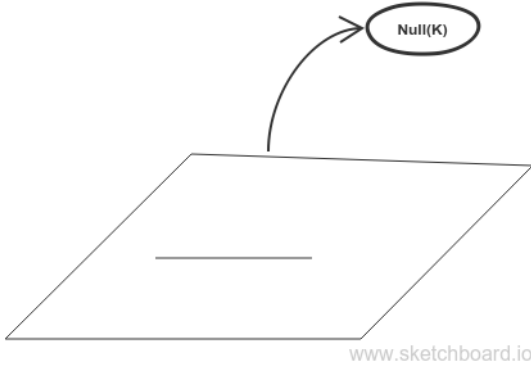
Observation 1.4.1 — Special case: Cone generated by $X \subset \mathbb{R}^n$. $\text{cone}(X) = \{\alpha x \mid x \in \text{ch}(X), \alpha \geq 0\} = \{y \mid y \in X, \alpha \in \mathbb{R}_+, y = \alpha^T x\}$



■ **Example 1.9 — Finitely generated cone.** $X = \{e_1, e_2, \dots, e_n\}$ where $e_i \in \mathbb{R}^n$ is a basis vector. Then $\text{cone}(X) = \mathbb{R}^n$ ■

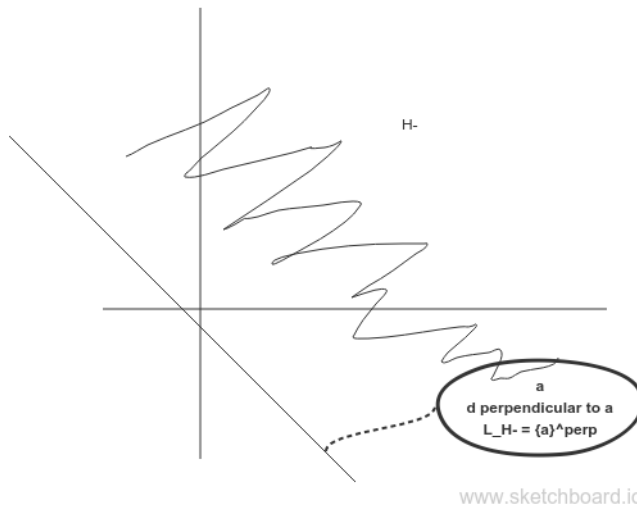
■ **Example 1.10 — Polyhedral cone.** For linear map A, B , $K = \{x \in \mathbb{R}^n \mid Ax \leq 0, Bx = 0\}$ ■

Generalize notion of linear subspace, for example $\text{null}(B)$ is special cone.



■ **Example 1.11 — Lineality space.** Linear space of a convex set C , $L_C = \{d \mid x + \alpha d \in C \forall x \in C, \forall \alpha\}$.

Lineality space of polyhedral $\text{cone}(K)$ is $L_K = \text{null} \begin{pmatrix} A \\ B \end{pmatrix}$. K is pointed iff $\text{rank} \begin{pmatrix} A \\ B \end{pmatrix} = n$.



Polar of a convex cone K , $K^c = \{y | \langle y, x \rangle \leq 0, \forall x \in K\}$

Polar cone and linear map

- $C \subset \mathbb{R}^n$ closed convex cone
- $A : \mathbb{R}^n \rightarrow \mathbb{R}^m$ linear map
- $K = A^{-1}(C) = \{x | Ax \in C\}$
- $K^c = \{z | z = A^T y, y \in C^c\}$

■ Example 1.12

$$C = \{0\}$$

$$K = \{x | Ax = 0\} = \text{null}(A)$$

$$K^c = \{z | z = A^T y, y \in \mathbb{R}^n = \{0\}\} = \text{range}(A^T)$$

■ Example 1.13

$$C = \mathbb{R}^n = \{y | y_i \leq 0\}$$

$$K = \{x | Ax \leq 0\}$$

$$K^c = \{z | z = A^T y, y \geq 0\}$$

Take any $x \in K, z \in K^c$, $\langle x, z \rangle = \langle x, A^T y \rangle = \langle Ax, y \rangle \leq 0$

Definition 1.4.1 — Projection onto a closed convex set. $P_c(x) = \arg \min \frac{1}{2} |z - x|^2$

Claim 1.4.2 Projection onto C is unique.

Suppose $y_1, y_2 \in P_c(x)$, if $y_1 \neq y_2$, take $y_0 = \frac{1}{2}(y_1 + y_2)$.

Proof.

$$\begin{aligned}\|x - \frac{1}{2}(y_1 + y_2)\|^2 &= \frac{1}{4}\|x - y_1 + x - y_2\|^2 \\ &= \frac{1}{2}(\|x - y_1\| + \|x - y_2\| - \frac{1}{2}\|y_1 - y_2\|)^2 \\ &< d - \frac{1}{4}\|y_1 - y_2\|^2\end{aligned}$$

■

Theorem 1.4.3 — Projection Theorem. $y_x = P_C(x) \Leftrightarrow \langle x - y_x, y - y_x \rangle \leq 0 \quad \forall y \in C$,
Suppose C is an affine manifold. $\langle x - y_x, y - y_x \rangle = 0$

- Proposition 1.4.4**
1. $\{x \in \mathbb{R}^n | x = P_C(x)\} = C$
 2. $P_C \circ P_C = P_C$. (Idempotent)
 3. $\|P_C(x_1) - P_C(x_2)\|^2 \leq \langle P_C(x_1), P_C(x_2), x_1, x_2 \rangle$
 - (a) $0 \leq \langle P_C(x_1) - P_C(x_2), x_1 - x_2 \rangle$
 - (b) Apply Cauchy to (3), $\|P_C(x_1) - P_C(x_2)\| \leq \|P_C(x_1) - P_C(x_2)\| \cdot \|x_1 - x_2\| \Rightarrow \|P_C(x_1) - P_C(x_2)\| \leq \|x_1 - x_2\|$
 - (c) If $0 \in C \Rightarrow \|P_C(x)\| \leq \|x\|$

1.5 Notes on January 23rd

Projection onto convex set $C \in \mathbb{R}^n$ $P_C(x) = \arg \min_{z \in C} \frac{1}{2}\|z - x\|^2$

Theorem 1.5.1 — Projection Theorem. $y_x = P_C(x) \Leftrightarrow \langle x - y_x, y - y_x \rangle \leq 0 \quad \forall y \in C$,
Suppose C is an affine manifold. $\langle x - y_x, y - y_x \rangle = 0$

Projection onto convex closed set $K \in \mathbb{R}^n$. $y_x = P_K(x) \Leftrightarrow y_x \in K, x - y_x \in K^\perp, \langle x - y_x, y_x \rangle = 0$

■ **Example 1.14** Now any ?? $K = \mathbb{R}_+^n, y_K = \max\{0, x_1\}$.

$$x - y_x = \begin{cases} 0 & x \geq 0 \\ x & x < 0 \end{cases}$$

■

Proof of ?? $\Rightarrow$

By PT, $y_x \in P_C(x) \Rightarrow \langle x - y_x, y - y_x \rangle \leq 0 \quad \forall y \in C$. Because $y \in K, y = \alpha y_x \forall \alpha > 0$.

$$\begin{aligned}0 &\geq \langle \alpha y_x - y_x, x - y_x \rangle \\ &= \langle (\alpha - 1)y_x, x - y_x \rangle \\ &= (\alpha - 1)\langle y_x, x - y_x \rangle\end{aligned}$$

$$\alpha - 1 \leq 0 \Rightarrow \langle y_x, x - y_x \rangle = 0$$

(*) implies $\langle y, x - y_n \rangle \leq 0 \forall K$

■

Consequences

$$P_K(x) = 0 \iff x \in K^o$$

$$P_K(\alpha x) = \alpha P_K(x) \forall \alpha > 0$$

$$P_K(\alpha x) = \arg \min_{z \in C} \frac{1}{2} \|z - \alpha x\| = \arg \min_{z \in C} \frac{1}{2} \|z/\alpha - x\| \alpha P_K(\alpha x) = \dots???$$

Proposition 1.5.2 The following are equal

1. $x = x_1 + x_2$ with $x_1 \in K, x_2 \in K^o, \langle x_1, x_2 \rangle = 0$
2. $x_1 = P_x(x), x_2 = P_{K^o(x)}$

1.6 Optimal Conditions for Unconstrained optimization

$\max_{x \in \mathbb{R}^n} f(x)$ $f: \mathbb{R}^n \rightarrow \mathbb{R}$ continuous on all $\mathbb{R}^n$.

■ **Example 1.15** $f(x) = e^{-x}$

The function is not coercive

Theorem 1.6.1 — Weierstrass Extreme Value . Every continuous function on compact set achieves its extreme value on that set.

R Caution to apply on $\mathbb{R}^n$, it's closed but not compact.

Definition 1.6.1 — coercive. The function $f: \mathbb{R}^n \rightarrow \mathbb{R}$ is coercive if for any sequence in $\{x^k\} \subset \mathbb{R}^n$ diverges $\Rightarrow f(\{x^k\})$ also diverges.

Theorem 1.6.2 — Coercivity and compactness. Let $f: \mathbb{R}^n \rightarrow \mathbb{R}$ and all $\mathbb{R}$. Then f is coercive $\iff S_x \|x\| f(x) \leq \alpha$ are compact for each $\alpha \in \mathbb{R}$

Proof. Assume S_x not bdd, $\exists \{x^k\} \in S_x$ such that $\|x^k\| \rightarrow \infty$. Since f is coercive, $\|f(x^k)\| \rightarrow \infty$ ■

Theorem 1.6.3 — Coercivity implies. let $f: \mathbb{R}^n \rightarrow \mathbb{R}$ be continuous, If f is coercive, P has at least one global solution

Proof. Coercivity implies S_x is compact

Weierstrauss implies $\min\{f(x) | x \in S_x\}$ has at least one minimizer.

$\arg \min_{x \in \mathbb{R}^n} f(x) \supset \{f(x) | x \in S_x\}$ ■

■ **Example 1.16 — Simple function not coercive.** $f(x) = \frac{1}{2} \|Ax - b\|^2$

If A is not full rank, f is not continuous. Take $x^k \in \text{NULL}(A)$, $\|x^k\| \rightarrow \infty$ but $f(x^k) = \frac{1}{2} \|b\|^2$. There's still global maxima even the function is not coercive. ■

1.6.1 First Order Optimality Condition

Reduce to a one dimensional case. Take $\phi(\alpha) = f(x + \alpha d)$ for some $x, d \in \mathbb{R}^n$. Direction of derivative, $f'(x, d) = \lim_{\alpha \rightarrow 0} \frac{f(x + \alpha d) - f(x)}{\alpha}$. When f is differentiable, then $f'(x, d) = \nabla f(x)^T d = \phi'(\alpha)$ If

$f'(x, d) < 0$, by continuity of f , $\exists \bar{\alpha} > 0$ s.t. $\frac{f(x + \alpha d) - f(x)}{\alpha} < 0 \forall \alpha \in (0, \bar{\alpha})$.

$\Rightarrow f(x + \alpha d) < f(x) \forall \alpha \in (0, \bar{\alpha})$.

Lemma 1.6.4 — 1st order optimality. Let $f: \mathbb{R}^n \rightarrow \mathbb{R}$ be a local solution to P. Then $f'(x, d) \geq 0, \forall d \text{ s.t. } f'(x, d) \geq 0$

Theorem 1.6.5 Let f differentiable at $\bar{x} \in$. If $\bar{x}$ is a local min. $\nabla f(\bar{x}) = 0$

Proof. $0 \leq f'(\bar{x}, d) = \nabla f(\bar{x})^T d \forall d$.

Take $d = -\nabla f(\bar{x})$

$0 \leq \nabla f(\bar{x})^T d = -\nabla f(\bar{x})^T \nabla f(\bar{x}). \|\nabla f(\bar{x})\| \leq 0 \Rightarrow \|\nabla f(\bar{x})\| = 0$ ■